

## Solutions to H/W 4

a)  $t_1 = t, t_2 = \varepsilon t \Rightarrow d_t \rightarrow \partial_1 + \varepsilon \partial_2 \Rightarrow y \sim y_0 + \varepsilon y_1 + \dots$

$$(\partial_1^2 + 2\varepsilon \partial_1 \partial_2 + \varepsilon^2 \partial_2^2)(y_0 + \varepsilon y_1 + \dots) + y_0 + \varepsilon y_1 + \dots + \varepsilon^2 y_0 + \dots = 0$$

O(1)  $\partial_1^2 y_0 + y_0 = 0 \Rightarrow y_0 = A(t_2) \cos[t_1 + \theta(t_2)]$

$$y_0|_{t=0, \theta=0} = a \quad \partial_1 y_0|_{t=0, \theta=0} = 0 \quad A(0) \cos \theta(0) = a \quad A(0) \sin \theta(0) = 0$$

O(ε)  $\partial_1^2 y_1 + y_1 = -2\partial_1 \partial_2 y_0 - y_0^3$   
 $= 2(A' \sin + A\theta' \cos) - A^3 \cdot \frac{1}{4} [3 \cos \theta + \cos 3\theta]$

sin:  $2A' = 0 \Rightarrow A = \text{const} = A_0$

cos:  $2A\theta' - \frac{3}{4}A^3 = 0 \Rightarrow \theta' = \frac{3}{8}A^2 \Rightarrow \theta = \frac{3}{8}A^2 t_2 + \theta_0$

$$y_0 = A_0 \cos[t_1 + \frac{3}{8}A_0^2 t_2 + \theta_0] \quad \Rightarrow \quad \text{Ics} \Rightarrow A_0 = a \\ = a \cos[(1 + \frac{3}{8}a^2 \varepsilon)t]$$

b)  $y \sim y_0 + \varepsilon y_1 + \varepsilon^2 y_2 + \dots \Rightarrow$

$$y_0'' + \varepsilon y_1'' + \varepsilon^2 y_2'' + \dots + y_0 + \varepsilon y_1 + \varepsilon^2 y_2 + \dots + \varepsilon(y_0^2 + 2\varepsilon y_0 y_1 + \dots) = 0$$

O(1)  $y_0'' + y_0 = 0 \Rightarrow y_0 = a \cos t$

$$y_0|_{t=0} = a, y_0'|_{t=0} = 0$$

O(ε)  $y_1'' + y_1 = -y_0^2 = -\frac{1}{2}a^2[1 + \cos 2t]$

$$y_1 = A \cos t + B \sin t - \frac{1}{2}a^2 + \frac{1}{6}a^2 \cos 2t \quad \left. \begin{array}{l} \text{no secular} \\ \text{terms} \end{array} \right\}$$

O(ε²)  $y_2'' + y_2 = -2y_0 y_1 = -2a \cdot \text{cost} \cdot [A \cos t + B \sin t - \frac{1}{2}a^2 + \frac{1}{6}a^2 \cos 2t]$

↑  
will produce a secular term

c)  $t_1 = t, t_2 = \varepsilon^2 t \quad \& \quad y \sim y_0 + \varepsilon y_1 + \varepsilon^2 y_2 + \dots \Rightarrow$

$$(\partial_1^2 + 2\varepsilon^2 \partial_1 \partial_2 + \varepsilon^4 \partial_2^2)(y_0 + \varepsilon y_1 + \varepsilon^2 y_2 + \dots) + y_0 + \varepsilon y_1 + \varepsilon^2 y_2 + \dots$$

$$+ \varepsilon(y_0^2 + 2\varepsilon y_0 y_1 + \dots) = 0$$

z

$$\text{O(1)} \quad \ddot{y}_0 + y_0 = 0 \Rightarrow y_0 = A_0(t_0) \cos [t_0 + \theta_0(t_0)]$$

$$y_0|_{t=0} = a, \dot{y}_0|_{t=0} = 0 \quad A_0(t_0) \cos \theta_0(t_0) = a$$

$$\cdot \sin \theta_0(t_0) = 0$$

$$\text{O}(z) \quad \ddot{y}_1 + y_1 = -y_0^2 = -A_0^2 \cdot \frac{1}{2} [1 + \cos 2(t_0 + \theta_0)]$$

$$y_1 = A_1(t_0) \cos [t_0 + \theta_1(t_0)] - \frac{1}{2} A_0^2 + \frac{1}{6} A_0^2 \cos 2(t_0 + \theta_0)$$

$$\text{O}(\varepsilon^2) \quad \ddot{y}_2 + y_2 = -2y_0 y_1 - 2\dot{y}_0 \dot{y}_1$$

$$= -2(A_0 \sin t_0 + A_0 \theta_0 \cos t_0) - 2A_0 \cos [A_0 t_0 - \frac{1}{2} A_0^2 + \frac{1}{6} A_0^2 \cos 2(t_0 + \theta_0)]$$

$$= -2(A_0 \sin t_0 + A_0 \theta_0 \cos t_0) + A_0^3 \cos t_0 - \frac{1}{3} A_0^3 \left[ \frac{1}{2} \cos(t_0 + \theta_0) + \frac{1}{2} \cos 3(t_0 + \theta_0) \right]$$

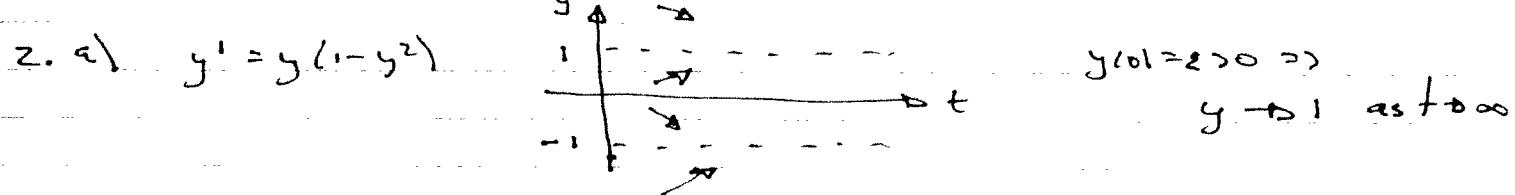
$$\sin: \quad A_0' = 0 \Rightarrow A_0 = \text{const}$$

$$\cos: \quad 2A_0 \theta_0' + A_0^3 - \frac{1}{6} A_0^3 = 0 \Rightarrow \theta_0' = -\frac{5}{12} A_0^2 \Rightarrow \theta_0 = -\frac{5}{12} A_0^2 t_0 + \varphi_0$$

$$y_0 = A_0 \cos \left[ t_0 - \frac{5}{12} A_0^2 t_0 + \varphi_0 \right] \quad \xrightarrow{\text{ICs}} \quad A_0 = a$$

$$\varphi_0 = 0$$

$$= a \cdot \cos \left[ \left( 1 - \frac{5}{12} a^2 \varepsilon^2 \right) t \right]$$



$$\text{b) } y \approx \sum y_0 + \varepsilon^2 y_1 + \dots \Rightarrow \sum y_0' + \varepsilon^2 y_1' + \dots = \varepsilon y_0 + \varepsilon^3 y_1 + \dots - (\varepsilon^3 y_0^3 + \dots)$$

$$\text{O}(\varepsilon) \quad y_0' \leftarrow y_0 \Rightarrow y_0 = e^t$$

$$y_0|_{t=0} = 1$$

$$\text{O}(\varepsilon^3) \quad y_1' = y_1 - y_0^3 = y_1 - e^{3t}$$

$$\Rightarrow y_1 = -\frac{1}{2} e^{3t} + B e^t, \quad y_1|_{t=0} = 0$$

$$= \frac{1}{2} (e^{3t} - e^{3t}) = \frac{1}{2} e^{3t} (1 - e^{-3t})$$

$$\Rightarrow y \approx e^t \cdot \left[ 1 + \frac{1}{2} \varepsilon^2 (1 - e^{-3t}) \right]$$

• secular terms - grows exponentially - not algebraically

$$c) t_1 > t, \quad t_2 = \varepsilon^2 f(t) \Rightarrow \dot{y}_t \rightarrow \dot{y}_1 + \varepsilon^2 f' \cdot \dot{y}_2$$

$$y \sim \varepsilon y_0 + \varepsilon^3 y_1 + \dots \Rightarrow$$

$$(\dot{y}_1 + \varepsilon^2 f' \dot{y}_2)(\varepsilon y_0 + \varepsilon^3 y_1 + \dots) = \varepsilon y_0 + \varepsilon^3 y_1 + \dots - (\varepsilon^3 y_0 + \dots)$$

$$\mathcal{O}(\varepsilon) \quad \dot{y}_1 y_0 = y_0 \quad \Rightarrow \quad y_0 = A(t_2) e^{t_2} \\ y_0|_{t_0=0}=1 \quad A(0)=1$$

$$\mathcal{O}(\varepsilon^3) \quad \dot{y}_1 y_1 + \underbrace{f' \cdot \dot{y}_2 y_0}_{f' \cdot A' e^{t_2}} = y_1 - y_0^3 = y_1 - A^3 e^{3t_2}$$

$$\text{want } f' \dot{y}_2 y_0 = -A^3 e^{3t_2} \Rightarrow f' = e^{2t_2} \Rightarrow f = \frac{1}{2} [e^{2t_2} - 1]$$

$$\Rightarrow A' = -A^3 \Rightarrow -\frac{dA}{A^3} = dt_2 \Rightarrow \frac{1}{2A^2} = t_2 + B$$

$$A = \frac{\pm 1}{\sqrt{2(t_2 + B)}} \quad \Rightarrow \quad A|_{t_0=0}=1 > 0 \Rightarrow + \neq B = \frac{1}{2}$$

$$\Rightarrow y_0 = \frac{1}{\sqrt{1+2t_2}} e^{t_2} \quad \Rightarrow \quad \cancel{y_0}$$

$$= \frac{e^{t_2}}{\sqrt{1+\varepsilon^2 (e^{2t_2}-1)}}.$$

$$3 b) \quad m_1 y_1'' + h_1 y_1 = \varepsilon f$$

$$m_2 y_2'' + h_2 y_2 = -\varepsilon f$$

$$\frac{1}{t_{20}} f' + \frac{1}{c_0} f = y_2' - y_1'$$

$$t_1 = t, \quad t_2 = \varepsilon t \Rightarrow \dot{y}_t = \dot{y}_1 + \varepsilon \dot{y}_2$$

$$\Rightarrow y_1 \sim Y_1 + \varepsilon Z_1 \quad \text{and} \quad y_2 \sim Y_2 + \varepsilon Z_2 \quad \text{and} \quad f \sim f_0 + \dots$$

$$[m_1(\dot{y}_1^2 + 2\varepsilon \dot{y}_1 \dot{y}_2 + \varepsilon^2 \dot{y}_2^2) + h_1](Y_1 + \varepsilon Z_1 + \dots) = \varepsilon f_0 + \dots$$

$$[m_2(\dot{y}_1^2 + 2\varepsilon \dot{y}_1 \dot{y}_2 + \varepsilon^2 \dot{y}_2^2) + h_2](Y_2 + \varepsilon Z_2 + \dots) = -\varepsilon f_0$$

$$\frac{1}{t_{20}} f_0' + \frac{1}{c_0} f_0 = \dot{y}_1(Y_2 - Y_1)$$

$$OC(1) \quad (m_i \omega_i^2 + k_i) Y_i = 0 \Rightarrow Y_i = A_i \cos[\omega_i t_i + \theta_i] \quad i=1,2$$

$$\omega_i = \sqrt{\frac{k_i}{m_i}}$$

$$\begin{aligned} \frac{1}{k_0} \partial_1 f_0 + \frac{1}{c_0} f_0 &= \partial_1 [A_2 \cos(\omega_2 t_1 + \theta_2) - A_1 \cos(\omega_1 t_1 + \theta_1)] \\ &= -\omega_2 A_2 \sin(\omega_2 t_1 + \theta_2) + \omega_1 A_1 \sin(\omega_1 t_1 + \theta_1) \end{aligned}$$

$$f_p = \alpha_1 \sin(\omega_1 t_1 + \theta_1) + \beta_1 \cos(\omega_1 t_1 + \theta_1) + \alpha_2 \sin(\omega_2 t_1 + \theta_2) + \beta_2 \cos(\omega_2 t_1 + \theta_2)$$

$\Rightarrow$

$$\begin{aligned} \frac{1}{k_0} [\omega_1 \alpha_1 \cos_1 - \omega_1 \beta_1 \sin_1 + \omega_2 \alpha_2 \cos_2 - \omega_2 \beta_2 \sin_2] \\ + \frac{1}{c_0} (\alpha_1 \sin_1 + \beta_1 \cos_1 + \alpha_2 \sin_2 + \beta_2 \cos_2) = -\omega_2 A_2 \sin_2 + \omega_1 A_1 \sin_1 \end{aligned}$$

$$C_1: \frac{1}{k_0} \cdot \omega_1 \alpha_1 + \frac{1}{c_0} \beta_1 = 0 \Rightarrow \beta_1 = -\alpha_1 \cdot \frac{\omega_1 c_0}{k_0}$$

$$S_1: \frac{1}{k_0} (-\omega_1 \beta_1) + \frac{1}{c_0} \cdot \alpha_1 = \omega_1 A_1$$

$$\Rightarrow \alpha_1 = \frac{\omega_1 A_1}{\frac{1}{c_0} + \frac{\omega_1}{k_0} \cdot \frac{\omega_1 c_0}{k_0}} = \bar{\alpha}_1 A_1 \quad \bar{\alpha}_1 = \frac{c_0 \omega_1}{1 + (\omega_1 \frac{c_0}{k_0})^2}$$

$$\beta_1 = -\bar{\alpha}_1 A_1 \quad \bar{\beta}_1 = \frac{\omega_1 c_0}{k_0} \cdot \bar{\alpha}_1$$

Similarly

$$\alpha_2 = -\bar{\alpha}_2 A_2 \quad \beta_2 = \bar{\beta}_2 A_2$$

$$\therefore f_0 = f_p + Y_C$$

$$\text{Note } \partial_1 \partial_2 Y_1 = -\omega_1 A_1' \sin \omega_2 - \omega_1 A_1 \theta_1' \cos \omega_2$$

$$\partial_1 \partial_2 Y_2 = -\omega_2 A_2' \sin \omega_1 - \omega_2 A_2 \theta_2' \cos \omega_1$$

$$OC(2) \quad (m_2 \omega_2^2 + k_2) Z_2 + 2m_2 \partial_1 \partial_2 Y_1 = f_0$$

$$(m_2 \omega_2^2 + k_2) Z_2 + 2m_2 \partial_1 \partial_2 Y_2 = -f_0$$

$$\#1: \sin: z_{m_1}(-\omega_1 t_1') = \alpha_1 = \bar{\alpha}_1 A_1 \Rightarrow A_1 = A_{1,0} e^{-j_1 t_2} \\ \cos: z_{m_1}(-\omega_1 t_1 \theta_1') = \beta_1 = -\bar{\beta}_1 A_1 \Rightarrow j_1 = \bar{\alpha}_1 / z_{m_1} \omega_1$$

$$\theta_1' = \frac{\bar{\beta}_1}{z_{m_1} \omega_1} \Rightarrow \theta_1 = \frac{\bar{\beta}_1}{z_{m_1} \omega_1} t_2 + \theta_{1,0}$$

$$\#2: \sin: z_{m_2}(-\omega_2 t_2') = -\alpha_2 = \bar{\alpha}_2 A_2 \Rightarrow A_2 = A_{2,0} e^{-j_2 t_2} \\ \cos: z_{m_2}(-\omega_2 t_2 \theta_2') = -\beta_2 = -\bar{\beta}_2 A_2 \Rightarrow j_2 = \bar{\alpha}_2 / z_{m_2} \omega_2$$

$$\theta_2' = \frac{\bar{\beta}_2}{z_{m_2} \omega_2} \Rightarrow \theta_2 = \frac{\bar{\beta}_2}{z_{m_2} \omega_2} t_2 + \theta_{2,0}$$

$$\therefore y_1 \sim A_{1,0} e^{-j_1 t_2} \cos[\omega_1 t_1 + \gamma_1 t_2 + \theta_{1,0}]$$

$$y_2 \sim A_{2,0} e^{-j_2 t_2} \cos[\omega_2 t_1 + \gamma_2 t_2 + \theta_{2,0}]$$

$$j_i = \frac{\bar{\alpha}_i}{z_{m_i} \omega_i} \quad \gamma_i = \frac{\bar{\beta}_i}{z_{m_i} \omega_i}$$

$$\bar{\alpha}_i = \frac{\cos \omega_i}{1 + \left( \frac{\omega_i \cos}{\omega_{i,0}} \right)^2} \quad \bar{\beta}_i = \frac{\omega_i \cos}{\omega_{i,0}} \cdot \bar{\alpha}_i$$